

1. Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be a linear transformation given by the matrix  $A = \begin{bmatrix} 2 & 0 & -1 \\ 1 & 1 & 0 \end{bmatrix}$ .

(a) Compute the Jacobian  $\mathbf{D}f(x, y, z)$ .

**Solution:** Notice that since  $A = \begin{bmatrix} 2 & 0 & -1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2x - z \\ x + y \end{bmatrix}$ , we can write  $f$  using function notation, namely  $f(x, y, z) = (2x - z, x + y)$ . Thus the Jacobian is

$$\mathbf{D}f(x, y, z) = \begin{bmatrix} 2 & 0 & -1 \\ 1 & 1 & 0 \end{bmatrix}.$$

(b) Show that  $f$  (as defined above) is differentiable at any point  $(x_0, y_0, z_0) \in \mathbb{R}^3$  by using the limit definition of differentiability.

**Solution:** Let  $\mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$  and  $\mathbf{x}_0 = \begin{bmatrix} x_0 \\ y_0 \\ z_0 \end{bmatrix}$ . Then

$$\begin{aligned} \lim_{\mathbf{x} \rightarrow \mathbf{x}_0} \frac{\|f(\mathbf{x}) - f(\mathbf{x}_0) - \mathbf{D}f(\mathbf{x}_0)(\mathbf{x} - \mathbf{x}_0)\|}{\|\mathbf{x} - \mathbf{x}_0\|} &= \lim_{\mathbf{x} \rightarrow \mathbf{x}_0} \frac{\left\| \begin{bmatrix} 2x - z \\ x + y \end{bmatrix} - \begin{bmatrix} 2x_0 - z_0 \\ x_0 + y_0 \end{bmatrix} - \begin{bmatrix} 2(x - x_0) - (z - z_0) \\ (x - x_0) + (y - y_0) \end{bmatrix} \right\|}{\|\mathbf{x} - \mathbf{x}_0\|}} \\ &= \lim_{\mathbf{x} \rightarrow \mathbf{x}_0} \frac{\left\| \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\|}{\|\mathbf{x} - \mathbf{x}_0\|} = \lim_{\mathbf{x} \rightarrow \mathbf{x}_0} 0 = 0. \end{aligned}$$

Thus  $f$  is differentiable at all points.

(c) A quicker way to show differentiability is to appeal to Theorem 9 in Section 2.3, which roughly states that if the partial derivatives of  $f$  exist at a point and they are continuous in a neighborhood of the point, then  $f$  is differentiable at the point. Apply this theorem to show  $f$  is differentiable at all points  $(x_0, y_0, z_0) \in \mathbb{R}^3$ .

**Solution:** Since the partial derivatives exist and are continuous at all points in  $\mathbb{R}^3$ ,  $f$  is automatically differentiable at all points, by the theorem.

2. Let  $f(x, y) = -\sqrt[3]{xy}$ . In class, we studied the graph of  $f$  and observed that  $\frac{\partial f}{\partial x}(0, 0)$  and  $\frac{\partial f}{\partial y}(0, 0)$  exist and that  $f$  is not differentiable at  $(0, 0)$ . In this problem, you will concretely show these facts.

(a) Show that  $\frac{\partial f}{\partial x}(0, 0)$  and  $\frac{\partial f}{\partial y}(0, 0)$  exist. (Hint: use the limit definition of partial derivatives)

**Solution:** 
$$\frac{\partial f}{\partial x}(0, 0) = \lim_{h \rightarrow 0} \frac{f(0 + h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = \lim_{h \rightarrow 0} 0 = 0.$$

Similarly, 
$$\frac{\partial f}{\partial y}(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, 0 + h) - f(0, 0)}{h} = 0.$$

(b) Show that  $f$  is not differentiable at  $(0, 0)$  by using the definition of differentiability.

**Solution:** To show  $f$  is not differentiable, we must show the following limit is not 0.

$$\lim_{(x,y) \rightarrow (0,0)} \frac{f(x,y) - f(0,0) - \frac{\partial f}{\partial x}(0,0)(x-0) - \frac{\partial f}{\partial y}(0,0)(y-0)}{\|(x,y) - (0,0)\|} = \lim_{(x,y) \rightarrow (0,0)} \frac{-\sqrt[3]{xy}}{\sqrt{x^2 + y^2}}.$$

As  $(x, y) \rightarrow (0, 0)$  along the line  $y = x$ , we have that  $\frac{-\sqrt[3]{xy}}{\sqrt{x^2 + y^2}} = \frac{x^{\frac{2}{3}}}{\sqrt{2}|x|} = \frac{1}{\sqrt{2}|x^{\frac{1}{3}}|} \rightarrow \infty$ .

Thus the limit does not exist and so  $f$  is not differentiable at  $(0, 0)$ .

(c) Once again recall Theorem 9 in Section 2.3 of the textbook, which states that if  $\frac{\partial f}{\partial x}(0, 0)$  and  $\frac{\partial f}{\partial y}(0, 0)$  exist and the partial derivatives are continuous in a neighborhood of  $(0, 0)$ , then  $f$  must be differentiable at  $(0, 0)$ . What can you conclude about the partial derivatives of  $f$  in light of this theorem and your findings in parts (a) and (b)?

**Solution:** Since the partial derivatives exist at  $(0, 0)$ , but  $f$  is not differentiable at  $(0, 0)$ , the partial derivatives cannot be continuous in a neighborhood of the origin.

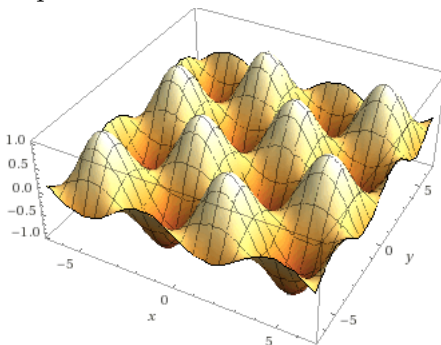
3. Give an example of a function  $f : \mathbb{R} \rightarrow \mathbb{R}$  with domain  $\mathbb{R}$  that is  $C^4$  but not  $C^5$ . Explain your reasoning.

**Solution:** Let  $f(x) = x^{\frac{9}{2}}$ . Then  $f^{(4)}(x) = \frac{945}{16}x^{\frac{1}{2}}$ , which is continuous on  $\mathbb{R}$ , but  $f^{(5)}(x) = \frac{945}{32}x^{-\frac{1}{2}}$ , which is not continuous at  $x = 0$ .

4. Let  $g(x, y) = \sin x \sin y$ .

(a) Graph  $g$  on <https://www.wolframalpha.com>. You'll notice that  $g$  looks like an infinite egg carton with infinitely many critical points. Based on the graph, what types of critical points (maxima, minima, saddles) does  $g$  have?

**Solution:** Based on the graph obtained from wolframalpha.com shown below,  $g$  has local maxima, minima, and saddle points.



(b) Find one critical point of each type that you found in part (a). Show your work.

**Solution:** Setting the partial derivative  $\frac{\partial g}{\partial x} = \cos x \sin y$  equal to zero, we have that either  $x = \frac{(2n+1)\pi}{2}$  or  $y = n\pi$ , where  $n$  is any integer. Similarly, setting  $\frac{\partial g}{\partial y} = \sin x \cos y$  equal to zero and solving, we have either  $x = n\pi$  or  $y = \frac{(2m+1)\pi}{2}$ . Thus the critical points are of the form  $(n\pi, m\pi)$  and  $(\frac{(2n+1)\pi}{2}, \frac{(2m+1)\pi}{2})$ , where  $n$  and  $m$  are any integers. Consider the critical points  $(0, 0)$ ,  $(\frac{\pi}{2}, \frac{\pi}{2})$ , and  $(\frac{3\pi}{2}, \frac{\pi}{2})$ . The Hessian of  $g$  is

$$Hg(x, y) = \begin{bmatrix} -\sin x \sin y & \cos x \cos y \\ \cos x \cos y & -\sin x \sin y \end{bmatrix}.$$

At  $(0, 0)$ , we have

$$\det Hg(0, 0) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = -1 < 0.$$

Thus  $f$  has a saddle point at  $(0, 0)$ . At  $(\frac{\pi}{2}, \frac{\pi}{2})$ , we have that

$$\det Hg(\frac{\pi}{2}, \frac{\pi}{2}) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = 1 > 0 \text{ and } \frac{\partial^2 f}{\partial x^2}(\frac{\pi}{2}, \frac{\pi}{2}) = -1 < 0.$$

Thus  $f$  has a local maximum at  $(\frac{\pi}{2}, \frac{\pi}{2})$ . Finally, at  $(\frac{3\pi}{2}, \frac{\pi}{2})$ , we have that

$$\det Hg(\frac{3\pi}{2}, \frac{\pi}{2}) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 1 > 0 \text{ and } \frac{\partial^2 f}{\partial x^2}(\frac{3\pi}{2}, \frac{\pi}{2}) = 1 > 0.$$

Thus  $f$  has a local minimum at  $(\frac{3\pi}{2}, \frac{\pi}{2})$ .

5. Let  $h(x, y) = x^4 - y^2$ . Show that  $h$  has a degenerate critical point at  $(0, 0)$ . In class, we discussed how to determine the concavity in the  $x$ - and  $y$ -directions around a degenerate critical point. What can you say about the concavity of  $h$  in the  $x$ - and  $y$ -directions around the point  $(0, 0)$ ? Explain your reasoning. Graph  $h(x, y) = x^4 - y^2$  on <https://wolframalpha.com> to graphically check your work (this last part is for your benefit. You do not have to submit this graph).

**Solution:** Since  $\frac{\partial^2 h}{\partial x^2}(x, 0) = 12x^2 \geq 0$ ,  $h$  is concave up in the  $x$ -direction. Since  $\frac{\partial^2 h}{\partial y^2}(0, y) = -2 < 0$ ,  $h$  is concave down in the  $y$ -direction.

6. Let  $f(x, y, z) = x^2 + \frac{1}{3}y^3 + z^2 + 2yz$ . Find and classify the critical points of  $f$ . What is the index of each critical point?

**Solution:**  $\frac{\partial f}{\partial x} = 2x$ ,  $\frac{\partial f}{\partial y} = 2y^2 + 2z$ ,  $\frac{\partial f}{\partial z} = 2z + 2y$ . Setting these equal to 0, the first equation gives  $x = 0$  and the others give  $y^2 = -2z$  and  $z = -y$ . Combining these, we have  $y^2 = 2y \Rightarrow y(y - 2) = 0 \Rightarrow y = 0, 2$ . The corresponding  $z$ -values are  $0, -2$ . Thus the critical points are  $(0, 0, 0)$  and  $(0, 2, -2)$ .

The Hessian is  $H(x, y, z) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4y & 2 \\ 0 & 2 & 2 \end{bmatrix}$ .

At the critical points, we have  $H(0, 0, 0) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 2 & 2 \end{bmatrix}$  and  $H(0, 2, -2) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 8 & 2 \\ 0 & 2 & 2 \end{bmatrix}$ .

To classify and determine the index of the critical points, we can just find the eigenvalues of the above matrices.

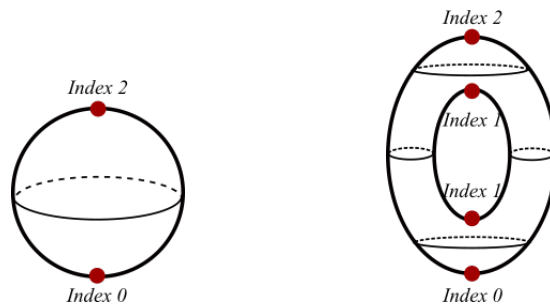
First, let's find the eigenvalues of  $H(0, 0, 0)$ :

$$\det \begin{bmatrix} 2 - \lambda & 0 & 0 \\ 0 & -\lambda & 2 \\ 0 & 2 & 2 - \lambda \end{bmatrix} = (2 - \lambda)[- \lambda(2 - \lambda) - 4] = 0 \Rightarrow \lambda = 2 \text{ or } \lambda^2 - 2\lambda - 4 = 0. \text{ Using}$$

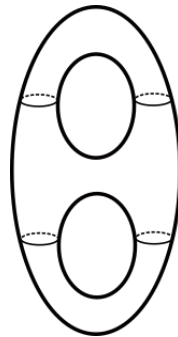
the quadratic formula to solve the second equation gives  $\lambda = 1 \pm \sqrt{5}$ . Now since two of the eigenvalues are positive and one is negative,  $H(0, 0, 0)$  is neither positive- nor negative-definite and so  $f$  has a saddle point at  $(0, 0, 0)$ . Moreover,  $(0, 0, 0)$  is an index 1 critical point.

Similarly, the eigenvalues of  $H(0, 2, -2)$  are 2 and  $5 \pm \sqrt{13}$ . Since these are all positive, the Hessian is positive-definite and so  $f$  has a local minimum at  $(0, 2, -2)$ . Moreover,  $(0, 2, -2)$  is an index 0 critical point.

7. In class we saw that a sphere can be built out of one index 0 critical point and one index 1 critical point and a torus (which is the surface of a donut) can be built out of one index 0 critical point, two index 1 critical points, and one index 2 critical point, as shown below.

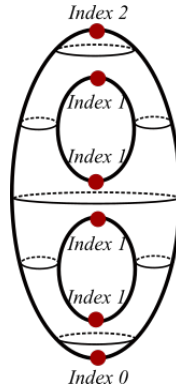


The *genus* of a surface  $\mathbb{R}^3$  with no boundary is the number of “donut holes” in the surface. So, the sphere is a surface of genus 0 and the torus a surface of genus 1. Let  $\Sigma_g$  be a surface of genus  $g$ . Following the example of the torus we did in class, how many critical points can  $\Sigma_2$  (which is shown below) be built out of? What are the indices of these critical points?



Let's generalize. How many critical points can  $\Sigma_g$  be built out of? What are the indices of these critical points? This is a conceptual problem and does not require the use of any functions.

**Solution:**  $\Sigma_2$  has one index 0 critical point, four index 1 critical points, and one index 2 critical points, as shown below.



More generally,  $\Sigma_g$  has one index 0 critical point,  $2g$  index 1 critical points, and one index 2 critical point.